

Control of Residential Inverter-type Air conditioners to Provide Regulation Services under Uncertainties

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• Introduction

- Motivation behind the work
- **Proposed Methodology** \bullet
- Results \bullet
- Future Work

Why we need Regulation services ?

The rapid growth of intermittent renewable energy generation urges the need of additional reserve capacity to manage the grid.

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What are Distributed Energy Resources (DERs) and why they are useful ?

https://aemo.com.au/en/initiatives/major-programs/nem-distributed-energy-resources-der-program

https://www.irena.org/-/media/Files/IRENA/Agency/Publication/2019/Feb/IRENA_Market_integration_distributed_system_2019.pdf?la=en&hash=2A67D3A224F1443D529935DF471D5EA1E23C774A

A glimpse of DR initiatives around the world

Trials have not been able to capture the residential DER aggregation.

Existing vs. Future prospects

Under-utilising the capacity of DER possessed by residential customers is a missed opportunity in electricity markets.

Why uncertainties need to be addressed?

Demand Response Standards

Load control algorithms in existing literature hardly take account of existing DR standards.

Drawbacks of existing load control programs

Why our primary focus is on Air-conditioning loads?

The capabilities of inverter-type air conditioners operating under demand response standards for regulation services requires further study.

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System Model

Using a first order thermal model (ETP model) for inverter-type air conditioners,

$$
T_i(k+1) = a_i T_i(k) + (1-a_i) \left[T_i^{\text{out}}(k) - \eta_i R_i P_i(k) \right]
$$

 $T_i(k)$: indoor temperature at time k

 $e^{out}(k)$: outdoor temperature at time k $T_i^{out}(k)$: outdoor temperature at time k

 $P_i(k)$: power consumption at time k

- R_{i} : thermal resistance
- C_i : thermal capacitance
- η_i : coefficient of performance

$$
a_i = e^{-h/R_iC_i}
$$

Individual models can be stacked together to obtain the aggregate model of the population of air conditioners (dynamically-decoupled).

$$
\mathbf{x}(k+1) = \mathbf{A}\mathbf{x}(k) + \mathbf{B}\mathbf{u}(k) + \mathbf{D}\mathbf{v}(k) + \mathbf{w}(k)
$$

$$
\mathbf{y}(k) = \mathbf{C}\mathbf{x}(k)
$$

[1] J. Mathieu, S. Koch and D. Callaway, "State estimation and control of electric loads to manage real-time energy imbalance," 13 2013 IEEE Power & Energy Society General Meeting, Vancouver, BC, 2013, pp. 1-1, doi: 10.1109/PESMG.2013.6672144.

obtained from [1]

Overall Robust Model Predictive Control (MPC) scheme

Centralised control scheme

Constraints of the problem

$$
\mathbf{x}(k+j+1|k) = A\mathbf{x}(k+j|k) + B\mathbf{u}(k+j|k) \n+ D\mathbf{v}(k+j|k) + \mathbf{w}(k+j|k) \nP_{agg}(k+j|k) = \mathbf{P}_{\text{rated}}\mathbf{u}(k+j|k) \n\frac{\chi \leq \mathbf{x}(k+j|k) \leq \overline{\chi}}{\Delta\mathbf{u}(k+j|k) = \mathbf{u}(k+j+1|k) - \mathbf{u}(k+j|k)} \n\qquad\n\frac{\text{Thermal comfort}}{\mathbf{u}(k+j|k) = \{0.5, 0.75, 1.0\}} \n\qquad\n\frac{\mathbf{w}(k+j|k) \in \mathbb{W}}{\mathbf{w}(k+j|k) \in \mathbb{W}} \n\qquad\n\text{for } j = 0, 1, 2...N - 1 \n\mathbb{W} = \{\mathbf{w} : ||\mathbf{w}||_{\infty} \leq \mathbf{w}_0\} \n\qquad\n\frac{\text{Worst-case distance distribution}}{\text{disturbance}}
$$

How to find the worst-case disturbance for Robust MPC scheme ? (w_0)

Deriving from first principles,

How to find the worst-case disturbance for
\nRobust MPC scheme ? (w₀)
\nDeriving from first principles,
\n
$$
R_i = R_{\text{nom},i} + \Delta R_i
$$
\n
$$
C_i = C_{\text{nom},i} + \Delta C_i
$$
\n
$$
a_i = e^{-h/(R_i C_i)} = e^{-h/(R_{\text{nom},i} + \Delta R_i)(C_{\text{nom},i} + \Delta C_i)}
$$
\n
$$
= e^{-h/(R_{\text{nom},i}C_{\text{nom},i} + R_{\text{nom},i}\Delta C_i + C_{\text{nom},i}\Delta R_i + \Delta R_i\Delta C_i)}
$$
\n
$$
a_i = a_{\text{nom},i} + \Delta a_i
$$
\n
$$
a_{\text{nom},i} = e^{-h/(R_{\text{nom},i}C_{\text{nom},i})}
$$
\n
$$
T_i(k+1) = (a_{\text{nom},i} + \Delta a_i)T_i(k) + (1 - (a_{\text{nom},i} + \Delta a_i))
$$
\n
$$
\left[(T_i^{\text{out}}(k) + \Delta T_i^{\text{out}}(k)) - \eta_i(R_{\text{nom},i} + \Delta R_i)P_i(k) \right]
$$
\n
$$
w_i(k) = (1 - a_{\text{nom},i})(\Delta T_i^{\text{out}}(k) - \eta_i \Delta R_i P_i(k)) - \Delta a_i \cdot \left(T_i^{\text{out}}(k) - \Delta T_i^{\text{out}}(k) - \eta_i(R_{\text{nom},i} + \Delta R_i)P_i(k) \right)
$$

$$
w_i(k) = (1 - a_{\text{nom},i}) \left(\Delta T_i^{\text{out}}(k) - \eta_i \Delta R_i P_i(k)\right) - \Delta a_i \cdot \left(T_i^{\text{out}}(k) - \Delta T_i^{\text{out}}(k) - \eta_i (R_{\text{nom},i} + \Delta R_i) P_i(k)\right)
$$

How to find the worst-case disturbance for Robust MPC scheme ? (w_0)

If we can estimate, If we can estimate,

 $\Delta C_i = |\Delta C_i|_{\text{max}}$

 $\Delta R_i = |\Delta R_i|_{\text{max}}$

Analysing historical data, we can estimate outdoor temperature prediction error ate outdoor ten (w_0)

 $\Delta T_i^{\text{out}}(k) = |\Delta T_i^{\text{out}}|_{\text{max}}$

Finally, we have an estimation of (w_0)

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Simulation data

Results

As the degree of uncertainty increases, most of the air conditioners tend to operate at their extreme limits to avoid temperature violations.

However, tracking is maintained.

Results (continued)

Under tightened temperature constraints and additive uncertainties assumed to be positive

Towards the end of the event, the tracking performance degrades in order to maintain the indoor temperature within the limits

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Future work

- ✓ Distributed control of air conditioners instead of centralised control
	- end-user privacy-preserving
	- thermal comfort preserving
	- taking into account uncertainties at household level

Thank You !

