

#### Control of Residential Inverter-type Air conditioners to Provide Regulation Services under Uncertainties

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#### • Introduction

- Motivation behind the work
- Proposed Methodology
- Results
- Future Work



#### Why we need Regulation services ?



The rapid growth of intermittent renewable energy generation urges the need of additional reserve capacity to manage the grid.



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### What are Distributed Energy Resources (DERs) and why they are useful ?



https://aemo.com.au/en/initiatives/major-programs/nem-distributed-energy-resources-der-program

https://www.irena.org/-/media/Files/IRENA/Agency/Publication/2019/Feb/IRENA\_Market\_integration\_distributed\_system\_2019.pdf?la=en&hash=2A67D3A224F1443D529935DF471D5EA1E23C774A



### A glimpse of DR initiatives around the world



#### Trials have not been able to capture the residential DER aggregation.



#### Existing vs. Future prospects



Under-utilising the capacity of DER possessed by residential customers is a missed opportunity in electricity markets.



### Why uncertainties need to be addressed?





#### Demand Response Standards



Load control algorithms in existing literature hardly take account of existing DR standards.



## Drawbacks of existing load control programs





## Why our primary focus is on Air-conditioning loads?



The capabilities of inverter-type air conditioners operating under demand response standards for regulation services requires further study.



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#### System Model

Using a first order thermal model (ETP model) for inverter-type air conditioners,

$$T_{i}(k+1) = a_{i}T_{i}(k) + (1-a_{i})\left[T_{i}^{\text{out}}(k) - \eta_{i}R_{i}P_{i}(k)\right]$$

 $T_i(k)$ : indoor temperature at time k  $T_i^{out}(k)$ : outdoor temperature at time k

 $P_i(k)$ : power consumption at time k

- $R_i$ : thermal resistance
- $C_i$ : thermal capacitance

 $\eta_i$  : coefficient of performance

 $a_i = e^{-h/R_i C_i}$ 

Individual models can be stacked together to obtain the aggregate model of the population of air conditioners (dynamically-decoupled).

$$\mathbf{x}(k+1) = \mathbf{A}\mathbf{x}(k) + \mathbf{B}\mathbf{u}(k) + \mathbf{D}\mathbf{v}(k) + \mathbf{w}(k)$$
$$\mathbf{y}(k) = \mathbf{C}\mathbf{x}(k)$$

[1] J. Mathieu, S. Koch and D. Callaway, "State estimation and control of electric loads to manage real-time energy imbalance," 13 2013 IEEE Power & Energy Society General Meeting, Vancouver, BC, 2013, pp. 1-1, doi: 10.1109/PESMG.2013.6672144.

obtained from [1]

Parameter	Value
R	1.5 -2.5°C/kW
С	1.5 -2.5 kWh/°C
$\eta$	2.5



#### Overall Robust Model Predictive Control (MPC) scheme





#### Centralised control scheme





#### Constraints of the problem

$$\begin{split} \mathbf{x}(k+j+1|k) &= A\mathbf{x}(k+j|k) + B\mathbf{u}(k+j|k) \\ &+ D\mathbf{v}(k+j|k) + \mathbf{w}(k+j|k) \\ P_{\text{agg}}(k+j|k) &= \mathbf{P}_{\text{rated}}^{\mathrm{T}}\mathbf{u}(k+j|k) \\ \hline \underline{\mathcal{X}} &\leq \mathbf{x}(k+j|k) \leq \overline{\mathcal{X}} \\ \Delta \mathbf{u}(k+j|k) &= \mathbf{u}(k+j+1|k) - \mathbf{u}(k+j|k) \\ \hline \mathbf{u}(k+j|k) &= \{0.5, 0.75, 1.0\} \\ \hline \mathbf{w}(k+j|k) \in \mathbb{W} \\ \text{for } j = 0, 1, 2 \dots N - 1 \\ \\ \mathbb{W} &= \{\mathbf{w} : \|\mathbf{w}\|_{\infty} \leq \mathbf{w}_0\} \\ \end{split}$$



#### How to find the worst-case disturbance for Robust MPC scheme $?(w_0)$

Deriving from first principles,

 $R_i = R_{\text{nom }i} + \Delta R_i$  $C_i = C_{\text{nom } i} + \Delta C_i$  $a_i = e^{-h/(R_i C_i)} = e^{-h/(R_{\text{nom},i} + \Delta R_i)(C_{\text{nom},i} + \Delta C_i)}$  $= e^{-h/(R_{\text{nom},i}C_{\text{nom},i} + R_{\text{nom},i}\Delta C_i + C_{\text{nom},i}\Delta R_i + \Delta R_i\Delta C_i)}$  $a_i = a_{\text{nom},i} + \Delta a_i$  $a_{\mathrm{nom},i} = e^{-h/(R_{\mathrm{nom},i}C_{\mathrm{nom},i})}$  $T_i(k+1) = (a_{\text{nom},i} + \Delta a_i)T_i(k) + (1 - (a_{\text{nom},i} + \Delta a_i))$  $\left[ \left( T_i^{\text{out}}(k) + \Delta T_i^{\text{out}}(k) \right) - \eta_i (R_{\text{nom},i} + \Delta R_i) P_i(k) \right]$ 

$$w_i(k) = (1 - a_{\text{nom},i}) \left( \Delta T_i^{\text{out}}(k) - \eta_i \, \Delta R_i \, P_i(k) \right) - \Delta a_i \cdot \left( T_i^{\text{out}}(k) - \Delta T_i^{\text{out}}(k) - \eta_i (R_{\text{nom},i} + \Delta R_i) P_i(k) \right)$$



#### How to find the worst-case disturbance for Robust MPC scheme $?(w_0)$

If we can estimate,

 $\Delta C_i = |\Delta C_i|_{\max}$ 

 $\Delta R_i = |\Delta R_i|_{\max}$ 

Remember!

Parameter	Value
R	1.5 -2.5°C/kW
С	1.5 -2.5 kWh/°C
$\eta$	2.5

Analysing historical data, we can estimate outdoor temperature prediction error

 $\Delta T_i^{\rm out}(k) = |\Delta T_i^{\rm out}|_{\rm max}$ 

Finally, we have an estimation of  $(w_0)$ 



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#### Simulation data

Parameter/ Variable	Value
P <sub>rated</sub>	2.5 kW
Temp constraints	[ 22, 24]°C
T <sub>set</sub>	23°C
Simulation step size	1 min
MPC prediction horizon (N)	3 mins
T <sub>duration</sub>	1 hour
No. houses $(n_h)$	1000



#### Results



As the degree of uncertainty increases, most of the air conditioners tend to operate at their extreme limits to avoid temperature violations.

However, tracking is maintained.



#### Results (continued)

Under tightened temperature constraints and additive uncertainties assumed to be positive



Towards the end of the event, the tracking performance degrades in order to maintain the indoor temperature within the limits



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#### Future work

- Distributed control of air conditioners instead of centralised control
  - end-user privacy-preserving
  - thermal comfort preserving
  - taking into account uncertainties at household level



# Thank You !

